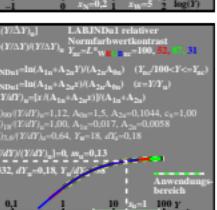
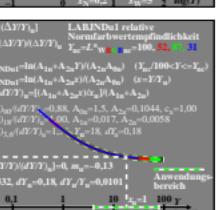
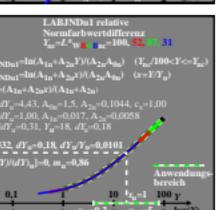
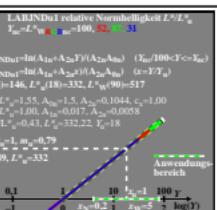
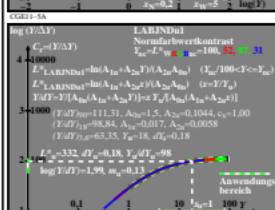
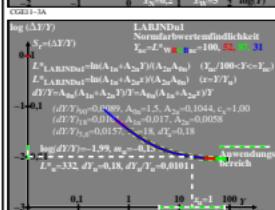
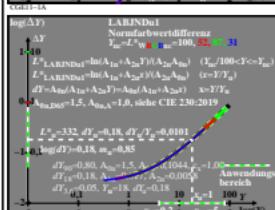
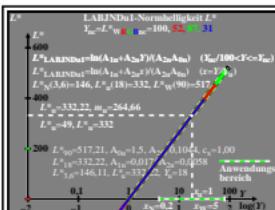
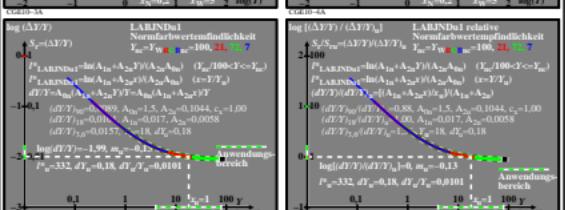
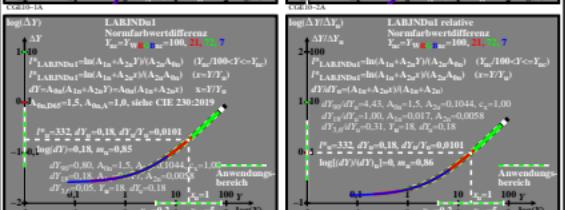
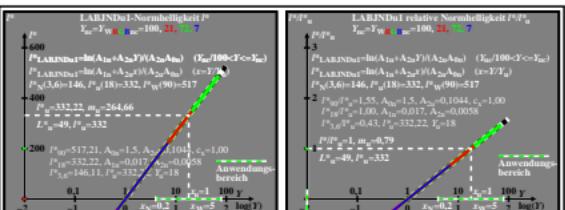


<http://farbe.li.tu-berlin.de/CGE1/CGE1L0N1.TXT> /PS; Start-Ausgabe
N: Keine 3D-Linearisierung (OL) in Datei (F) oder PS-Startup (S), Seite 1/1

Figure 1. The two main components of the model: the top part shows the state-space representation of the system, and the bottom part shows the corresponding state-space representation of the controller.



TUB-Präfvorlage CGE1; LABJNDu1, $I^*(Y)$ & $L^*(Y)$, $Y_{nc} = (Y \& L^*)^{Wnc}$, $c_X = 1,00$, mit mehr Daten
Absolute, relative Helligkeit, Empfindlichkeit, Kontrast, $A_{0n}=1,5$, $A_{1n}=0,017$, $A_{2n}=0,0058$, $A_{2u}=0,0005$

Absolute, relative Helligkeit, Empfindlichkeit, Kontrast, $A_{0n}=1,5$, $A_{1n}=0,017$, $A_{2n}=0,0058$, $A_{2u}=0,10$